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$$\begin{aligned}
c &= 3.0 \times 10^8 \text{ m/s} & G &= 6.67 \times 10^{-11} \text{ Nm}^2/\text{kg}^2 & g &= 9.8 \text{ m/s}^2 \\
R &= 8.315 \frac{\text{J}}{\text{mol} \cdot \text{K}} & k &= 1.38 \times 10^{-23} \frac{\text{J}}{\text{K}} & N_A &= 6.02 \times 10^{23} \\
1 \text{ ft} &= 12 \text{ in} & 1 \text{ in} &= 2.54 \text{ cm} & 1 \text{ lb} &= 0.454 \text{ kg} & 1 \text{ mi} &= 1.6 \text{ km} \\
I_o &= 10 \times 10^{-12} \frac{\text{W}}{\text{m}^2} & 1 \text{ atm} &= 1.013 \times 10^5 \text{ Pa} & 1 \text{ m}^3 &= 10^3 \text{ L} = 10^6 \text{ cm}^3 \\
1 \text{ cal} &= 4186 \text{ J} & 1 u &= 1.6605 \times 10^{-27} \text{ kg}
\end{aligned}$$


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$$\text{av. speed} = \frac{\text{distance traveled}}{\text{time elapsed}} \quad \bar{v} = \frac{x_2 - x_1}{t_2 - t_1} = \frac{\Delta x}{\Delta t} \quad \bar{a} = \frac{v_2 - v_1}{t_2 - t_1} = \frac{\Delta v}{\Delta t}$$

$$a = \text{const} \quad v = v_0 + at \quad x = x_0 + v_0t + \frac{at^2}{2} \quad v^2 - v_0^2 = 2a(x - x_0)$$

$$F_{fr} = \mu_k F_N \quad F_{fr} \leq \mu_s F_N$$

$$a = \frac{v^2}{r} \quad F = G \frac{m_1 m_2}{R^2} \quad \left(\frac{T_1}{T_2}\right)^2 = \left(\frac{a_1}{a_2}\right)^3$$

$$W = Fd \cos(\theta) \quad KE = \frac{mv^2}{2} \quad PE = mgh \quad PE = \frac{kx^2}{2}$$

$$\Delta E = W \quad P = \frac{\Delta E}{\Delta t} \quad P = F \cdot v$$

$$\sum \vec{F} = \frac{\Delta \vec{p}}{\Delta t} \quad \vec{J} = \vec{F} \Delta t \quad x_{C.M.} = \frac{m_1 x_1 + m_2 x_2 + m_3 x_3 + \dots}{m_1 + m_2 + m_3 + \dots}$$

$$\bar{\omega} = \frac{\Delta \theta}{\Delta t} \quad \bar{\alpha} = \frac{\Delta \omega}{\Delta t} \quad f = \frac{1}{T} \quad \omega = 2\pi f$$

$$\alpha = \text{const} \quad \omega = \omega_o + \alpha t \quad \theta = \theta_o + \omega_o t + \frac{\alpha t^2}{2} \quad \omega^2 = \omega_o^2 + 2\alpha \Delta \theta$$

$$\theta = \frac{l}{r} \quad v = \omega r \quad a = \alpha r$$

$$\tau = rF \sin \theta \quad \tau = I\alpha \quad KE_{rot} = \frac{I\omega^2}{2} \quad W = \tau \Delta \theta \quad P = \tau \omega$$

$$L = I\omega \quad L = r \cdot p_{\perp} = rp \sin \theta \quad \frac{\Delta L}{L} = \frac{1}{E} \frac{F}{A}$$


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$$P = P_o + \rho gy \quad F_b = \rho Vg \quad A_1 v_1 = A_2 v_2 \quad P + \rho gy + \frac{\rho v^2}{2} = \text{const.}$$


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$$x = A \cos(\omega t + \theta_o) \quad \omega^2 = \frac{k}{m} \quad T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{m}{k}} \quad f = \frac{1}{T} = \frac{\omega}{2\pi} = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$

$$T = 2\pi \sqrt{\frac{L}{g}} \quad E = \frac{kA^2}{2} \quad I \propto \frac{A^2}{r^2}$$

$$v = \lambda f \quad v = \sqrt{\frac{E_T}{\mu}} \quad v = 331 + 0.6T \quad \beta = 10 \log \frac{I}{I_o}$$


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$$n = \frac{N}{N_A} = \frac{m}{\mu} = \frac{V}{V_{\mu}} \quad T(^{\circ}\text{C}) = \frac{5}{9}(T(^{\circ}\text{F}) - 32) \quad T(^{\circ}\text{F}) = \frac{9}{5}T(^{\circ}\text{C}) + 32$$

$$\Delta L = \alpha L_o \Delta T \quad \Delta V = \beta V_o \Delta T \quad PV = nRT \quad PV = NkT$$

$$\langle KE \rangle = \frac{1}{2} m \langle v^2 \rangle = \frac{1}{2} m v_{rms}^2 = \frac{3}{2} kT \quad Q = mc \Delta T \quad Q = mL$$

$$\Delta U = Q - W \quad W = P \Delta V \quad e = \frac{|Q_H| - |Q_L|}{|Q_H|} \quad e = 1 - \frac{T_L}{T_H}$$


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Object	$I$	Object	$I$
thin loop	$MR^2$	(uniform rod through center)	$\frac{1}{12}MR^2$
solid cylinder	$\frac{1}{2}MR^2$	(uniform rod through end)	$\frac{1}{3}MR^2$
uniform sphere	$\frac{2}{5}MR^2$		